horizontal line

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Map Routing

**4th December 2018**

# OVERVIEW

In recent days, transportation applications to move from one place to another has been evolving rapidly. The use of data from many users helps to make transportation better. Especially in reducing transportation time and avoid heavy traffic roads.

In this project we provide Three versions of Dijkestra Algorithm(Normal Dijkestra, double ended Dijkestra, and Fibonnaci heap Dijkestra) to find the least time to move from the source location to the destination location, and find the path that achieves that time.

# GOALS

1. Learn an optimized version of Djikestra algorithm, and use it in the project.
2. Optimize the constant factor of the overall complexity of the algorithm to speed the running time using the double ended Dijkestra.

# SPECIFICATIONS

* The moving person walks with constant speed (5 km/h) in straight lines (from the source to the starting intersection and from the finishing intersection to the destination).
* The moving person cannot walk more than R meters to move from the source location to the starting intersection. They also cannot walk more that R meters to move from the finishing intersection to the destination location.
* The time to get in a vehicle or get out of a vehicle is negligible (is not taken into consideration).
* The moving person will ride only one vehicle. They cannot get out of the vehicle unless they reached the final node.
* The vehicle always moves with the road speed. It changes speed only if the road is changed.
* The roads connect intersection in straight lines. They are also bidirectional roads.

# MILESTONES

## Milestone 1

1. Construct a weighted graph for the map.
2. The search for the optimal path to move from the source location to the destination location (small and medium cases).
3. Each query output should contain 5 lines as the following:

* The shortest time to move from the source location to the destination location (in minutes)
* The total distance of the path with the shortest time (in kilometers)
* The total walking distance (in kilometers)
* The total vehicle distance (in kilometers)
* The total execution time

1. Documentation I

## Milestone 2

1. Building the optimal path (output the nodes in order).
2. The project should work in all cases (small, medium, and large cases).
3. Documentation II